



Quick Reference

Keys - Overview



Device ON/OFF

| | |
|----------------------------|----------------|
| Medium push (2s) | Power ON / OFF |
| Very Long push (8s) | Reboot device |

During measurement

| | |
|-------------------|---|
| Short push | Arming the probe – start / resume measurement |
| Short push | Disarming the probe – stop measurement |



Bluetooth dongle

Battery

USB-C

Hammers

Low frequency hammer



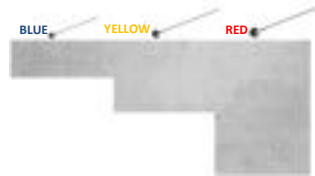
High frequency hammer (3 types)
7.5mm, 10mm and 15mm



| Ball Diameter, mm | Approximate Contact Time, μ s | Maximum Usable Frequency, kHz | Minimum Measurable * Depth, mm |
|-------------------|-----------------------------------|-------------------------------|--------------------------------|
| 5 | 22 | 47 | 43 |
| 6 | 26 | 39 | 52 |
| 7 | 30 | 33 | 60 |
| 8 | 34 | 29 | 69 |
| 9 | 39 | 26 | 77 |
| 10 | 43 | 23 | 86 |
| 12 | 52 | 19 | 105 |
| 15 | 65 | 16 | 129 |
| 20 | 86 | 12 | 172 |

*This is the minimum thickness of a structural element than can be measured

*It also refers to the minimum depth of a flaw that can be detected. All flaws above this depth will not be visible



Select the smaller hammer for thinner elements, and the bigger hammer for wider elements

LED - Behaviour



| LED behaviour | | |
|--|---------------------------------|--|
| Battery Status (when turning on the device) | Green: single quick blink: >20% | |
| | Red: single quick blink: <20% | |
| Turn on , awaiting Bluetooth connection | Green pulsing | |
| Connected , awaiting arming (disarmed) <ul style="list-style-type: none">PausedStopped | Blue pulsing | |
| Armed <ul style="list-style-type: none">Resumed | Blue Solid | |
| While measuring (rod/wheels) | Blue Solid | |
| Errors | | |
| Error | Red pulsing | |
| Device in boot loader mode | Red-Green alternate pulsing | |
| Battery Charging | | |
| While Charging | Green pulsing 0.5Hz | |
| Charged done | Green solid | |
| Error <ul style="list-style-type: none">batteries not charging / not insertedOvertoltage / overheated | Red solid | |

One Sensor – Two Applications

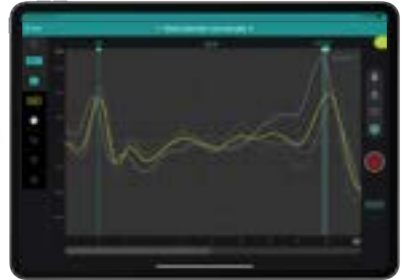
Pile Integrity Test

Deep Foundations:

- Cast in place piles.
- Driven piles.

Detection:

- Piles with free end.
- Piles with toe in bedrock.
- Short piles.
- Necking.
- Bulging.
- Cracks and voids.



Impact Echo Test

Concrete elements:

- Slab on grade.
- Foundation slab.
- Roof, floors.
- Beams and columns.
- Concrete pavement.
- Walls.
- Tunnels.

Detection:

- Plate thickness and backwall.
- Cracks and voids.
- Delamination.
- Honeycombs.
- Debonding areas.
- PT duct voids.



Contact Solution – Coupling material

Pile Integrity Test

- Clean the surface from dirt and debris.
- Grind the surface to make it smoother.
- Place a small portion of putty (coupling material) in the sensor tip.
- Change the portion of putty once it gets dirty.
- Perform minimum 5-10 impacts per spot.



Putty

Impact Echo Test

- Clean the surface from dirt and debris.
- Grind the surface to make it smoother.
- **DRY CONTACT SOLUTION:** Place a silicon sticker (coupling material) in the sensor tip and use it as many times as wanted.
- Once it is broken, replace it with a new sticker and clean the sensor tip with the cleaning pen.
- If coupling is not achieved, use putty.
- Perform minimum 5-10 impacts per spot.



Cleaning pen



Sticker

Technical Principle

Pile Integrity Test



Impact Echo Test



First calibration of speed

Pile Integrity Test

- Select Pile Integrity Mode **(0)**.
- Input the expected length of the pile **(1)**.
- Perform 5-10 impacts at the top of the pile.
- Press the calibration button **(2)**.
- Revise that the length shown on the app **(3)** matches with the expected one.

* If the length of the element is not known, estimate a wave velocity of 4.000m/s.



(3) Measured length

(0) Measuring Mode

(1) Expected length

(2) Calibration button
Wave velocity

| Pulse Velocity | Concrete Quality |
|-------------------|------------------|
| > 4 500 m/s | Excellent |
| 3 500 - 4 500 m/s | Good |
| 2 500 - 3 500 m/s | Medium |
| < 2 500 m/s | Doubtful |

Impact Echo Test

- Select Impact Echo Spot / Grid mode **(0)**.
- Input the expected thickness of the concrete element **(1)**.
- Perform 5-10 impacts in the surface far away from the sides (lateral faces, construction joints, etc).
- Press the calibration button **(2)**.
- Revise that the thickness shown in the frequency peak **(3)** matches with the expected one.

* If the thickness of the element is not known, estimate a wave velocity of 4.000m/s



(3) Measured thickness

(0) Measuring Mode

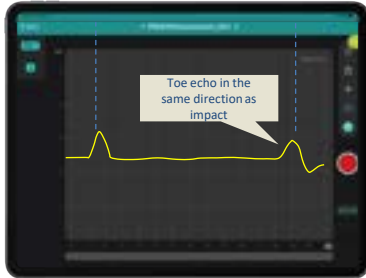
(1) Expected thickness

(2) Calibration button
Wave velocity

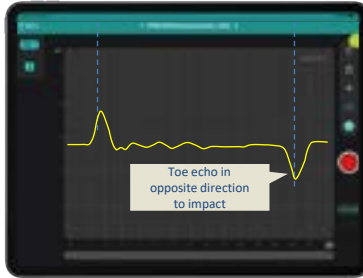
A few examples

Wave Integrity Test

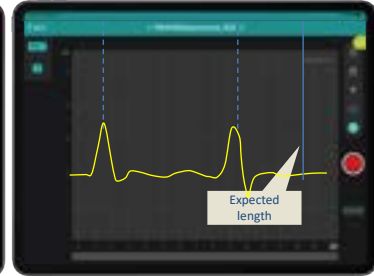
Pile with free end



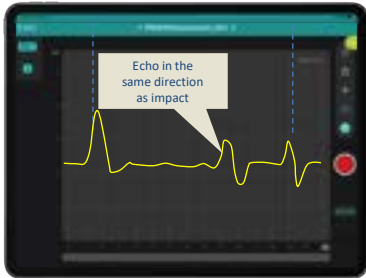
Toe in bedrock



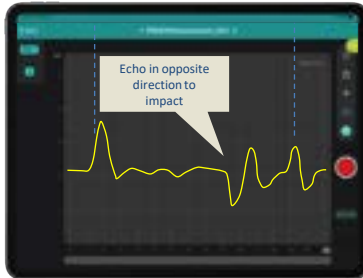
Short pile



Necking – reduction in diameter



Bulging – increase in diameter

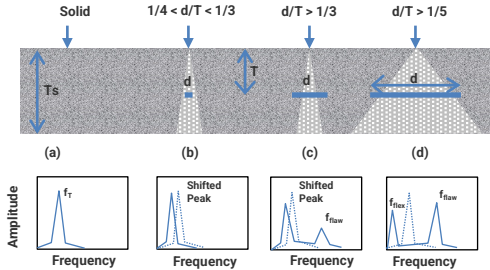


*These examples are shown as a reference only and are valid theoretically. However, the signal from a real case scenario can differ and it is the responsibility of the inspector to correctly identify and interpret it.

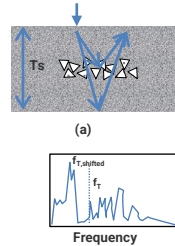
A few examples

Impact Echo Test

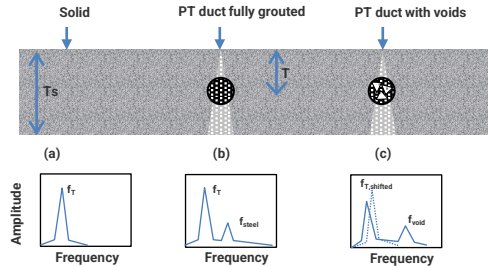
Cracks & Delamination



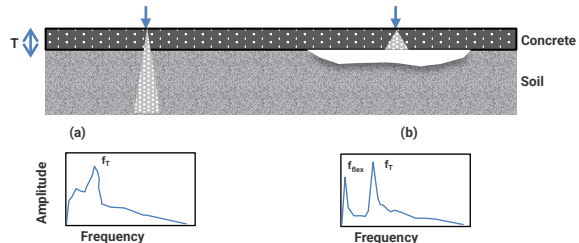
Honeycomb



Voids in post tensioning duct



Plates in contact with soil



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SWISS  MADE

For more information on the product use of the product,
please refer to the Product Name PI8000 documentation

It is available for download on



<https://www.screeningeagle.com/en/products/pundit-pi8000>

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